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Idea: consider the configuration space of pointsets



Pose DR in terms of state-space dynamics in the configuration space



Theoretical framework

Description of DR dynamics

Three examples of iDR

- DR tracking of time-varying input data
- introducing class knowledge
- interactive steering of DR parameters





steerable DR parameters

Further work Eigenmode analysis of DR dynamics

Local (linear) model around $\{\mathbf{y}_o, \mathbf{w}_o, \mathbf{x}_o\}$:

$$\dot{\mathbf{y}} = \mathbf{A}\mathbf{y} + \mathbf{B}\mathbf{u}$$

local stability and dynamics \rightarrow eigenmode analysis of

$$\mathbf{A} = \left. \frac{\partial f(\mathbf{y}, \mathbf{u})}{\partial \mathbf{y}} \right|_o$$